

Lecture 1

$$E_{\text{tot}} = \sum_i \frac{m_i v_i^2}{2} + U(r_1, \dots, r_n)$$

Momenta

$$p_i = m_i \dot{q}_i, \quad q^i := r_i$$

$$H = \sum_i \frac{p_i^2}{2m_i} + U(q^i, \varepsilon^N)$$

$\begin{bmatrix} r_1 \\ r_2 \\ \vdots \\ r_N \end{bmatrix} = \begin{bmatrix} q^1 \\ q^2 \\ \vdots \\ q^N \end{bmatrix}$

$\begin{cases} \dot{q}^i = \frac{p_i}{m_i} \\ \dot{p}_i = -\frac{\partial U}{\partial r_i} = -\frac{\partial H}{\partial q^i} \end{cases}$

$\frac{\partial H}{\partial p_i}$

$i(H, p) = \sum_{i=1}^N \frac{\partial H}{\partial q^i} \dot{q}^i + \sum_{i=1}^N \frac{\partial H}{\partial p_i} \dot{p}_i =$

$$= \sum_{i=1}^N \left(\frac{\partial H}{\partial q^i} \frac{\partial H}{\partial p_i} + \frac{\partial H}{\partial p_i} \left(-\frac{\partial H}{\partial q^i} \right) \right)$$

$$= 0.$$

That way a simple example
of Poisson geometry

$$M = T^* Q$$

$$p_i, q^i,$$

$$\{ \cdot, \cdot \} : C^\infty(M) \times C^\infty(M) \rightarrow C^\infty(M)$$

$$\{f_i, g_j\} = \sum_{i=1}^n \left(\frac{\partial f_i}{\partial q_j} \frac{\partial g_j}{\partial p_i} - \frac{\partial f_i}{\partial p_i} \frac{\partial g_j}{\partial q_j} \right)$$

$$-\{g_j, f_i\}$$

$$q = \pm \{q, H\}$$

$$p = \mp \{p, H\}$$

$$f(q, p) = \pm \{f, H\}$$

$$H(q, p) = \{H, H\} = 0$$

Exercise 1

This is also an example
of a symplectic space
 \hookrightarrow tomorrow

Exercise 2

$$1) H = \frac{q^2}{2} + \frac{p^2}{2}$$

R: Equations
and solve
them



$$2) H = \frac{p^2}{2m} + \cos q$$

R: Equations
and solve
them

typo, sorry
(but does not change the moral)

$$1) \begin{cases} \dot{q} = p \\ \dot{p} = -q \end{cases}$$

$\dot{q} + \dot{p} = 0$

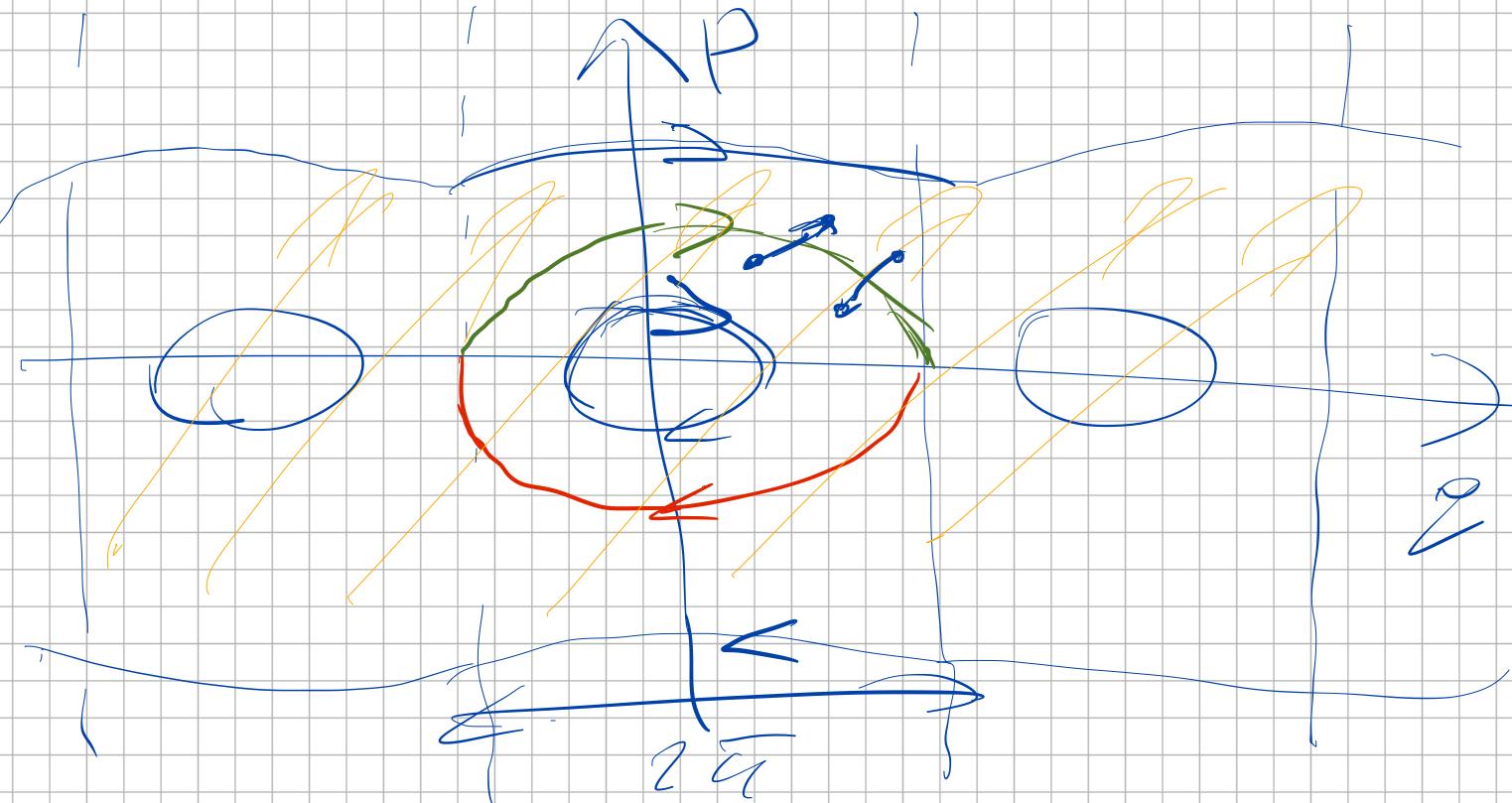
$q = A \cos t + B \sin t$

$q(0), p(0)$

$U = \text{const}$

$$2) \begin{cases} \dot{q} = p \\ \dot{p} = \sin \varphi \end{cases}$$

Elliptic functions



Lecture 2

$$q, \dot{q}, p \rightsquigarrow TQ \approx \mathbb{R}^{2N}$$

$$T^*Q \approx \mathbb{R}^{2N}$$

$$\mathbb{R}^N \times \mathbb{V}^N$$

$$\mathbb{R}^N \times (\mathbb{V}^*)^*$$

Hamiltonian

$$H \rightarrow \boxed{\{ \quad \}} \rightarrow$$

system of ODE

$$X_H = \left(\underbrace{\frac{\partial H}{\partial p_i}}_N, \underbrace{-\frac{\partial H}{\partial q^i}}_N \right)$$

a vector field
on (T^*Q)

solve the system of ODE

integrate X_H

final curve
in T^*Q s.t.

$$dH = \left(\begin{array}{c} \frac{\partial H}{\partial q^i} \\ \frac{\partial H}{\partial p_i} \end{array} \right)$$

$$dH = \sum_{i=1}^N \left(\frac{\partial H}{\partial q^i} dq^i + \frac{\partial H}{\partial p_i} dp_i \right)$$

They are related by

$$\underline{X_H = J dH}$$

$$\omega := J^{-1}$$

$$dH = \omega(X_H)$$

$$dH = L_{X_H} \omega$$

$$J = \begin{pmatrix} 0 & I_N \\ -I_N & 0 \end{pmatrix}$$

$$\omega = \pm \sum_{i=1}^N dq^i \wedge dp_i \quad [E_{\text{tot}}]$$

- 1) ω is non-degenerate \rightarrow symplectic
 2) $d\omega = 0$ \rightarrow closed

• Non deg $\Rightarrow H \rightarrow [\omega] \rightarrow X_H$

• Closed $\Rightarrow \omega$ is invariant
 by the flow of X_H

$$\begin{aligned} L_{X_H} \omega &= \cancel{\left(c_{X_H} d + d(c_{X_H}) \right)} \omega = \\ &= \cancel{c_x(d\omega)} + d \cancel{\left(c_{X_H} \omega \right)} = 0 \end{aligned}$$

L = 0

Exercise 2 (*)

$$\omega \xrightarrow{\mu \in \mathcal{M}} "f(\omega) - \omega"$$

Given ω , and a diff. eq.

ω and a vector field v

Let us say that v preserves ω

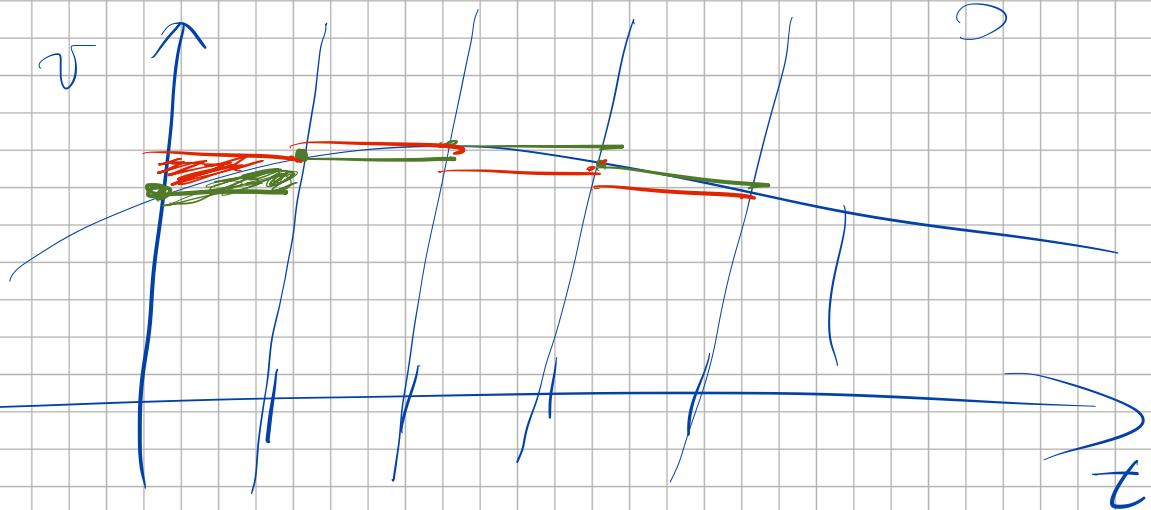
Can we say something about
 conservation of energy?

Numerics in 15 minutes

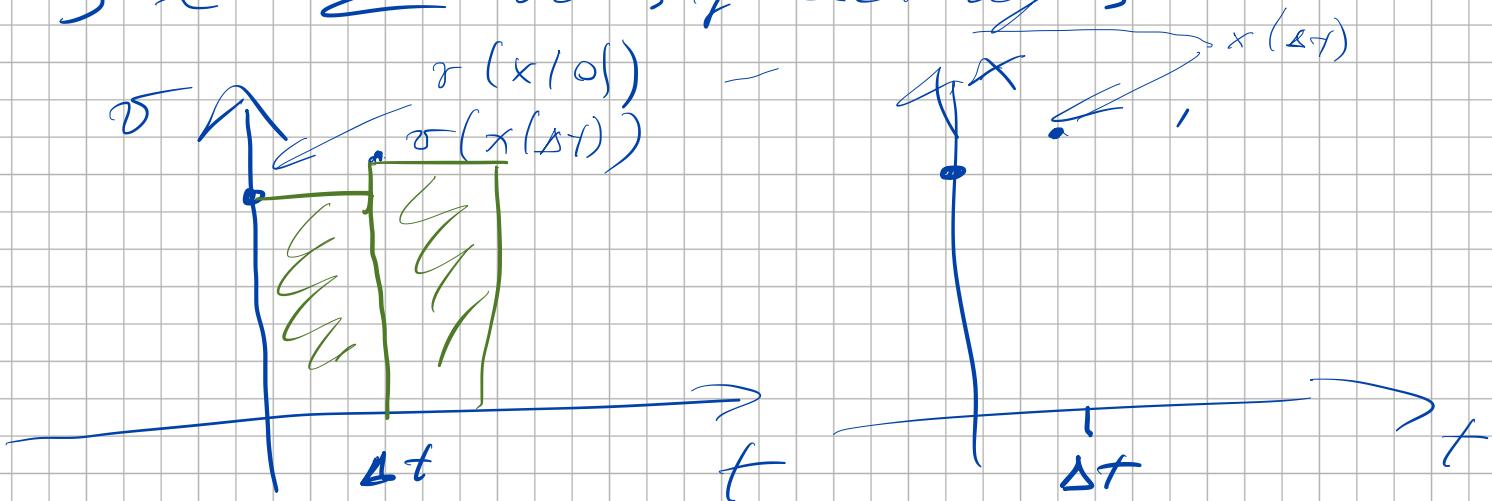
In 1D

$$\dot{x} = \varphi(x)$$

$$x(T) = x(0) + \int_0^T \varphi(x(t)) dt$$



$\int \approx \sum$ areas of rectangles



$$x(t+\Delta t) = x(t) + \Delta t \cdot \varphi(x(t))$$

$$x(t+\Delta t) = x(t) + \Delta t \cdot \varphi(x(t+\Delta t))$$

Euler Method

$$(F(x(t+\Delta t))) = 0$$

$$x = \begin{pmatrix} q_1 \\ q_2 \\ \vdots \\ q_N \end{pmatrix}$$

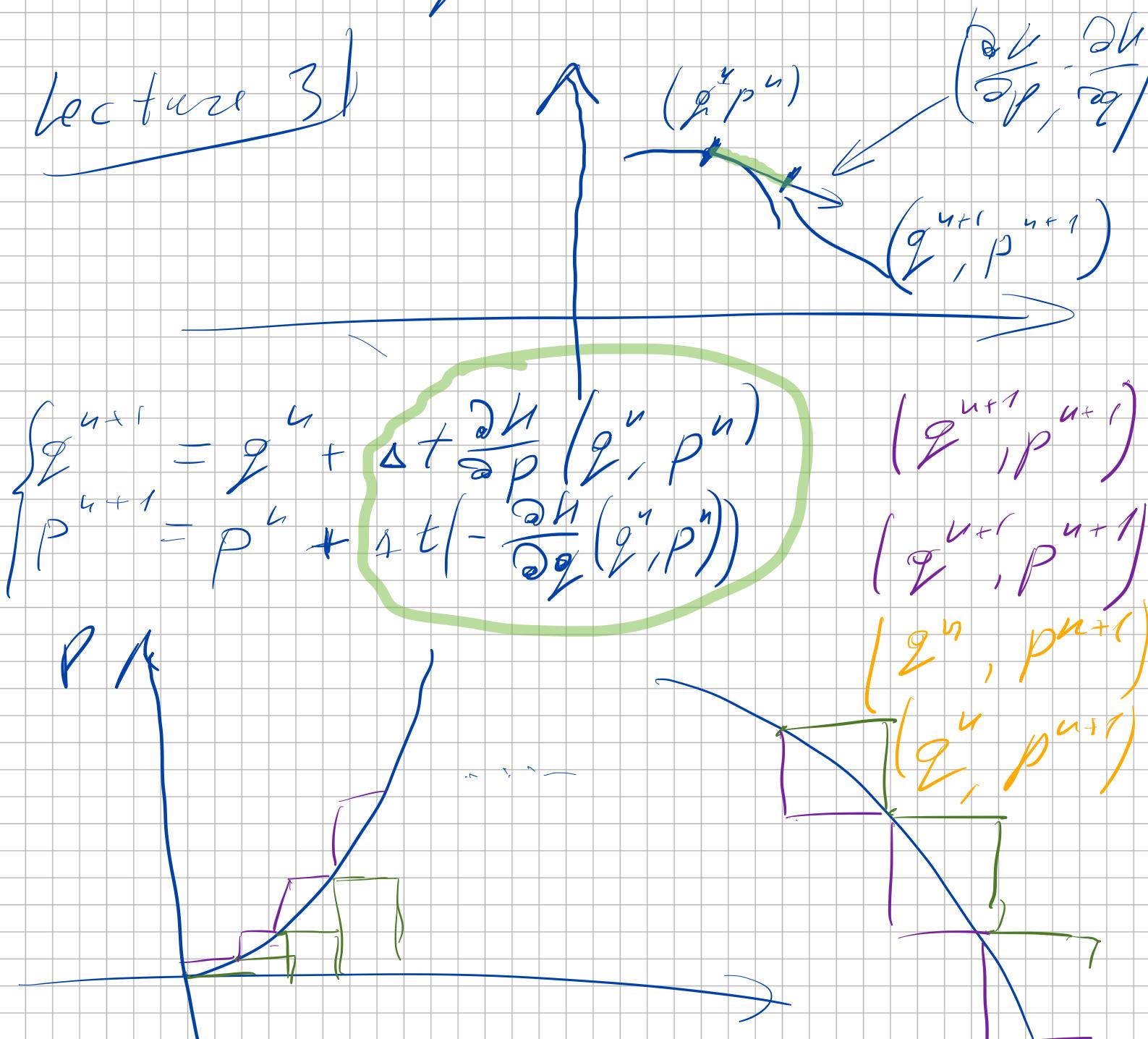
$$v = \begin{pmatrix} X_H \end{pmatrix}$$

Implicit Euler method

Exercise 3 (Hoher)

Do this for the exercises
1 & 2 from the
previous lectures

Lecture 3)



semi-explicit \rightsquigarrow symplectic

• From symplectic form to
energy

$\omega(\cdot, \cdot)$ non degenerate

closed $d\omega = 0$

\mathcal{V} -vector field $\underline{\mathcal{L}_{\mathcal{V}}\omega = 0 (*)}$

Q: H-energy, is it conserved
by the flow of \mathcal{V} ?

opposite no

Q: Given (*) can I find an
energy that is conserved

$$\cancel{\mathcal{L}_{\mathcal{V}}(d\omega) + d(\mathcal{L}_{\mathcal{V}}\omega) = 0}$$

$$\cancel{d} = 0 \quad \mathcal{L} = \mathcal{L}_{\mathcal{V}}\omega \equiv \omega(\mathcal{V}, \cdot)$$

$$dd = 0 \quad \cancel{\mathcal{L}} = \partial H$$

If there is no cohomology at
this degree (if there is no
difference between closed and
exact forms) then H .

Suppose $\boxed{\mathcal{L}_{\mathcal{V}}\omega = dH} \quad \mathcal{V} = X_4$

$$\mathcal{L}_{\mathcal{V}}H = \cancel{\mathcal{V}dH} = \cancel{\mathcal{L}_{\mathcal{V}}\mathcal{L}_{\mathcal{V}}\omega} = \omega(\mathcal{V}, \mathcal{V}) = 0$$

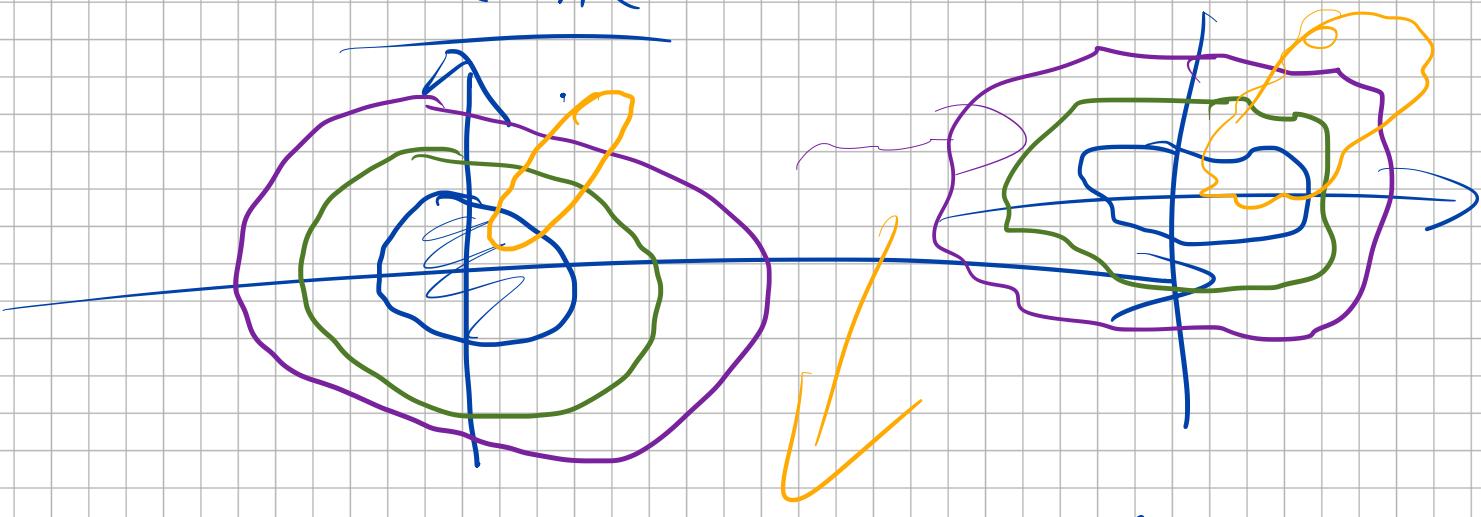
Take home message

1). ∇ preserving $\omega \rightsquigarrow \nabla = X_H$
(if some cond's)

2) if $\nabla = X_H \Rightarrow \nabla$ preserves
the level sets of H

Interpretation in 2D

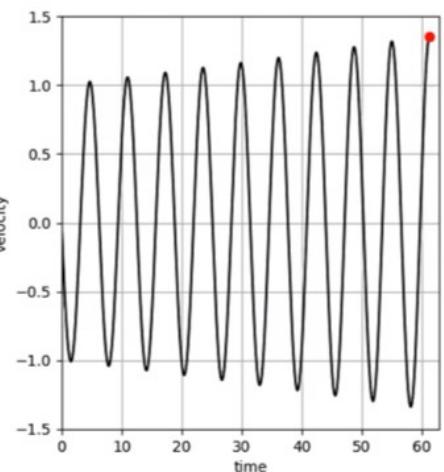
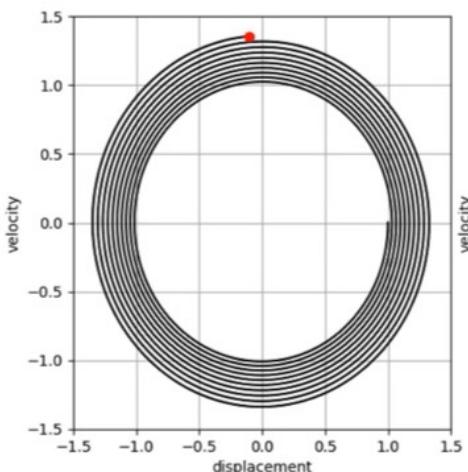
ω is the (oriented) area
in \mathbb{R}^2



preserve level sets

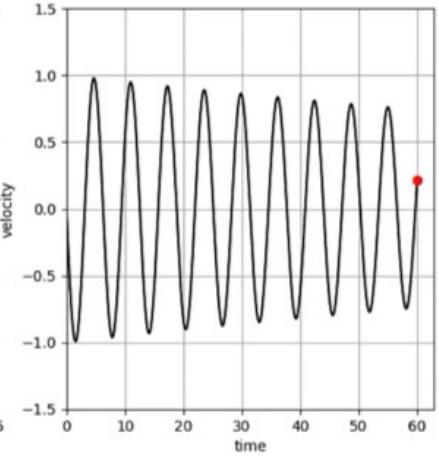
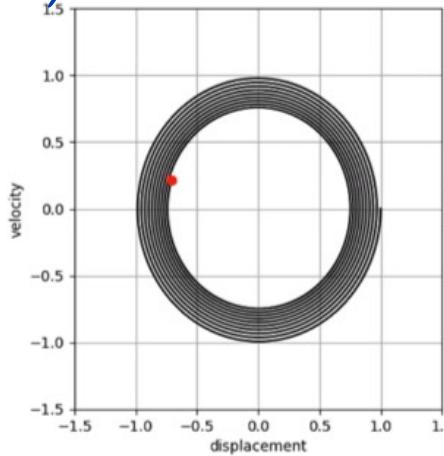
Explicit Euler for $H = \frac{q^2}{2} + \frac{p^2}{2}$

$$\begin{cases} \dot{q}^{n+1} = q^n + \Delta t \frac{\partial H}{\partial p}(q^n, p^n) \\ \dot{p}^{n+1} = p^n + \Delta t \left(-\frac{\partial H}{\partial q}(q^n, p^n) \right) \end{cases}$$



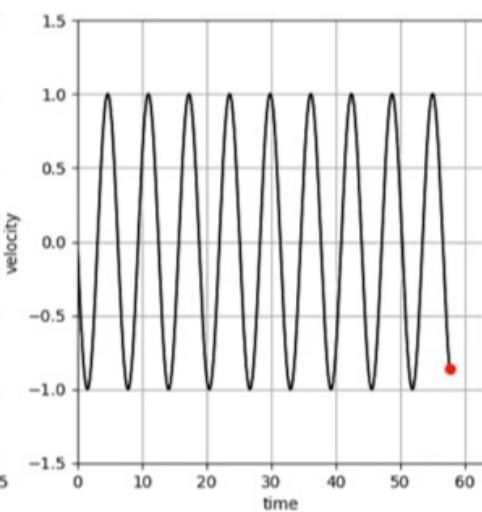
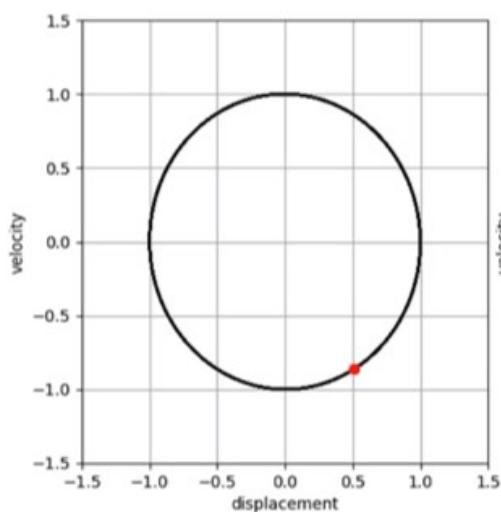
Implicit Euler

$$\begin{cases} \dot{q}^{n+1} = q^n + \Delta t \frac{\partial H}{\partial p}(q^{n+1}, p^{n+1}) \\ \dot{p}^{n+1} = p^n + \Delta t \left(-\frac{\partial H}{\partial q}(q^{n+1}, p^{n+1}) \right) \end{cases}$$



Symplectic Euler

$$\begin{cases} \dot{q}^{n+1} = q^n + \Delta t \frac{\partial H}{\partial p}(q^n, p^{n+1}) \\ \dot{p}^{n+1} = p^n + \Delta t \left(-\frac{\partial H}{\partial q}(q^n, p^{n+1}) \right) \end{cases}$$



Further reading

2. E. Hairer, C. Lubich, G. Wanner, Geometric Numerical Integration // Springer Series in Computational Mathematics, 2006.
3. D. Razafindralandy, A. Hamdouni, M. Chhay, A review of some geometric integrators // Advanced Modeling and Simulation in Engineering Sciences, SpringerOpen, 2018, 5 (1), pp.16.
4. J. E. Marsden, M. West, Discrete mechanics and variational integrators // Acta Numer. 10 (2001), 357–514.
5. V. Salnikov, A. Hamdouni, D. Loziienko, Generalized and graded geometry for mechanics: a comprehensive introduction // Mathematics and Mechanics of Complex Systems, Vol. 9, No. 1, 2021.
6. B. Сальников, А. Хамдуни, Дифференциальная геометрия и механика – источник задач для компьютерной алгебры // Программирование, 2020, № 2, с. 57–63

V.Salnikov, A.Hamdouni, Differential Geometry and Mechanics – a source of problems for computer algebra, Programming and Computer Software, Vol. 46, Issue 2, 2020.

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Thank you for
attention!