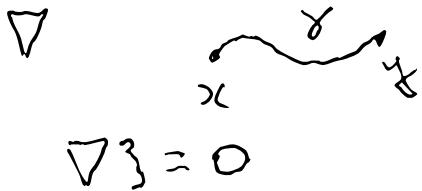


## Lecture 4

$E \downarrow M$



$$T_\gamma : E_x \rightarrow E_y$$



$\text{Hol}_\gamma(\nabla)$



$$E \rightarrow M \quad \nabla : R(X, Y) \mathcal{Z} := \nabla_X \nabla_Y \mathcal{Z} - \nabla_Y \nabla_X \mathcal{Z} - \nabla_{[X, Y]} \mathcal{Z}$$

$X, Y \in \Gamma(TM), \mathcal{Z} \in \Gamma(E)$

$$R : \Gamma(TM) \times \Gamma(TM) \times \Gamma(E) \rightarrow \Gamma(E)$$

$C^\infty_M$ -multilinear  $x \in R \quad R_x : T_x M \times T_x M \times E_x \rightarrow E_x$

$$R_x(X, Y) \mathcal{Z}_x$$

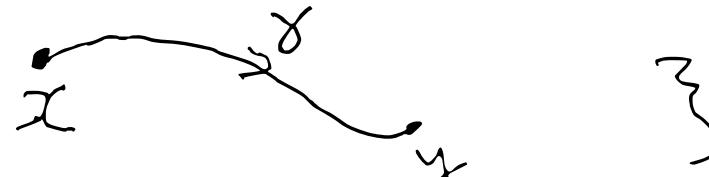
$\frac{d}{dt} \left( -T_{tx}^{-1} \circ T_{-tx} \circ T_{ty} \circ T_{tx} \right) \Big|_{t=0} \in \text{Hol}_x(\nabla)$

$$R(X, Y)$$

$$R(X, Y) : E_x \rightarrow E_x \quad X, Y \in T_x M$$

Th. (Ambrose - Singer)

$$\text{hol}_x(\nabla) = \text{span} \left\{ \underbrace{\nabla_x^{-1} \circ R_y(X, Y) \circ \nabla_x}_{E_y \rightarrow E_x} \mid \right.$$



$$\nabla_y: E_x \rightarrow E_y$$

Def  $\nabla$  is called flat if  $\forall x \in U$   
 $\exists \{z_1, \dots, z_m \in \Gamma(E|_U)\}$   $\nabla z_k = 0$

Th.  $\nabla$  is flat  $\Leftrightarrow R = 0 \Rightarrow \text{hol}_x^0(\nabla) = 0 \Leftrightarrow \text{Hol}_x^0(\nabla) = \{ \text{id} \}$

(1)

(2)

(3)

$= \{ \text{id} \}$

(2)  $\Rightarrow$  (3) A-S. Th.

(3)  $\Rightarrow$  (4) Lie Th.

$$(1) \Rightarrow (2) \quad R(X, Y) z_k = 0 \Rightarrow R(X, Y) = 0 \Rightarrow R = 0$$

$$(4) \Rightarrow (1) \quad \text{Hol}_x^0(\nabla) = \{ \text{id} \} \quad \begin{matrix} U \\ x \end{matrix} \quad \text{Hol}_x(\nabla|_U) = \{ \text{id} \}$$

$$\Rightarrow \exists z_1, \dots, z_m \in \Gamma(E_x) \quad \nabla z_k = 0 \quad \square$$

(\*)

$M \ni \gamma$  on  $TM$

$\gamma$  is defined  $T^{(p,q)}M$

$V$  be a vector space

$(1,0) X \in V$

$T_x M$

$T_x^{(p,q)} M$

$(0,1) \theta \in V^*$

$\theta(y) \in \mathbb{R}$

$T_x^* M$

$T^{(p,q)} M = \bigcup_{x \in M} T_x^{(p,q)} M$

$(0,2) \beta: V \times V \rightarrow \mathbb{R}$

$(1,2) \beta: V \times V \rightarrow V$

$(1,1) A: V \rightarrow V \quad A(x) \in V$

vector bundle over  $M$

$\psi(1,1) \forall x \in M$

$\psi_x: T_x M \rightarrow T_x M$

$\omega(0,1) \forall x \in M$

$\omega_x: T_x M \rightarrow \mathbb{R}$

: A tensor field  $(p,q)$

$\nabla_X A$

$\otimes(0,1) \theta \in \Gamma(T^*M)$

$(\nabla_X \theta)(Y) :=$

$:= X(\theta(Y))$

$x \xrightarrow{\delta} y$

$(T_\delta \theta_x)(X_y) = \theta_{x_1} (\Sigma_{j=1}^{-1} X_j)^{-1} \theta(X_y) \in \mathbb{R}$

$(M, g)$   $\models (0, 2)$   $\forall x \in M$   $g_x : T_x M \times T_x M \rightarrow \mathbb{R}$   
 symmetric, bil.  
 $\underline{g_x(x_i, x_j) > 0, x_i \neq 0}$  positive-definite  
 (Reind-Riem.) non-degenerate

$$(\nabla_X g)(Y, Z) = X(\underbrace{g(Y, Z)}_{-g(Y, \nabla_X Z)}) - g(\nabla_X Y, Z)$$

torsion  $T(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y]$

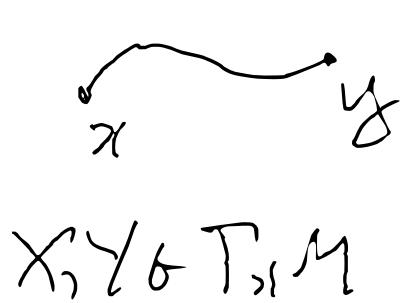
$X, Y \in \Gamma(TM)$   $T$  is def. only for comp. on  $TM$

Th:  $(M, g) \models ! \nabla$   $T(fX, Y) = fT(X, Y)$

1.  $\nabla g = 0$
2.  $T = 0$

*not torsion field*

Levi-Civita Connection



$$T_x g_x = g_y$$

$$g_x(X, Y) = g_y(T_x X, T_x Y)$$



$$g_x(T_x X, T_x Y) = g_x(X, Y)$$

$$\Rightarrow T_x \in O(T_x M, g_x) \cong O(n)$$

$$O(T_x M, g_x) = \{ Q : T_x M \rightarrow T_x M \mid g_x(\alpha X, \alpha Y) = g_x(X, Y) \}$$

$$Hol_x(g) \subset O(T_x M, g_x) = O(n)$$

$\circ$  Lie alg  $\circ \rightarrow \text{gl}(V)$

$\circ$  on  $\bigoplus^{(P, g)} V$

$V^*$

$A \in \mathfrak{g}$   $A: V \rightarrow V$

$$(A\theta)(X) = -\theta(AX)$$

$(0, z)$   $B: V \times V \rightarrow \mathbb{R}$

$$(A \cdot B)(X, Y) =$$

$$= -B(AX, Y) - B(X, AY)$$

$B$  is scalar  $\mathbb{R}^n$   
on  $\mathbb{R}^n$

$$A \in O(n) \Rightarrow A \cdot B = B$$

$(\cdot, \cdot)$

Cot.  $(M, \nabla)$

$\{A \otimes \text{T.f. } \alpha(P, g), \nabla A\} \hookrightarrow \{A_x \in \bigoplus_{T, M}^{(\alpha, \nabla)},$   
 $\alpha \cdot A_x = A_x$   
 $\nabla \alpha \in \text{Hol}(\nabla)\}$

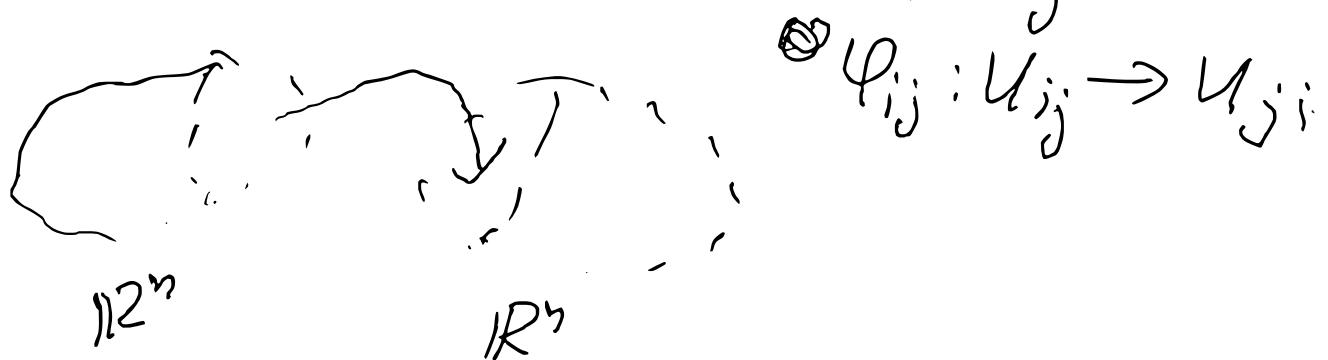
Prop.  $(M, g)$  Riem. mf.

$M$  is orientable  $\Leftrightarrow \text{Hol}_x(g) \subset SO(n)$

$$SO(n) = \{A \in O(n) \mid \det A = 1\}$$

$$\begin{array}{c} e_2 \\ \uparrow \\ \cdots \\ \downarrow \\ -\vec{e}_1 \end{array} \quad \begin{matrix} \text{id} \\ \diagup \\ \text{id} \end{matrix} \quad \begin{matrix} \text{id} \\ \diagup \\ \text{id} \end{matrix} \\ A = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \in O(2) \quad A: \mathbb{R}^n \rightarrow \mathbb{R}^n \\ \det A = -1 \end{array}$$

$M$  is orientable:  $\Leftrightarrow$  on  $M$   $U_i, U_j$



$\Leftrightarrow \exists$  non-vanishing  $n$ -form

$$\omega(x_1, x_2, \dots) = -\omega(x_2, x_1, \dots) \quad \underbrace{x_1, x_2, \dots, x_n}_{n \text{ times}} \rightarrow \mathbb{R}$$

$M$  is oriented  $\text{Vol} := \sqrt{\det|g_{ij}|} dx^1 \wedge \dots \wedge dx^n$

 $\nabla g = 0 \Rightarrow \nabla \text{Vol} = 0 \Rightarrow \text{Hol}_x \cdot \text{Vol}_x = \text{Vol}_x$ 
 $\Rightarrow \text{Hol}_x \subset SO(n)$ 

$\Leftarrow: \text{Hol}_x \subset SO(n) \exists \omega_x$  n-form

$$\text{Hol}_x \cdot \underline{\omega_x} = \underline{\omega_x}$$

$\Rightarrow \exists \omega \quad \nabla \omega = 0 \Rightarrow \omega$  is non-vanishing  
 $\Rightarrow M$  is orientable.  $\square$

$$(M, g) \leadsto \nabla$$

$$\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}$$

$$x^1, \dots, x^n$$

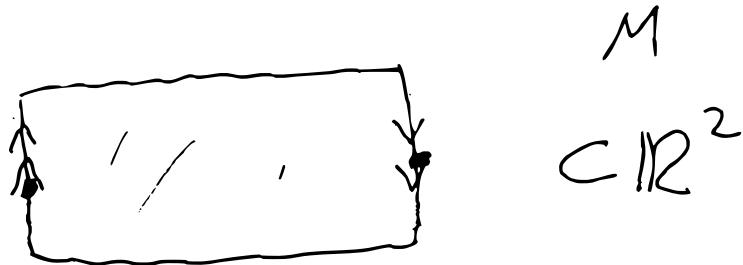
$$g_{ij} := g\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right)$$

$$\nabla_{\frac{\partial}{\partial x^i}} \frac{\partial}{\partial x^j} = \Gamma_{ij}^k \frac{\partial}{\partial x^k}$$

$$\nabla_{x_i^k} \frac{\partial}{\partial x^j} = \dots$$

$$\Gamma_{ij}^k = \frac{1}{2} g^{kl} \left( \frac{\partial g_{lj}}{\partial x^i} + \dots \right)$$

Möbius



$M$

$\subset \mathbb{R}^2$

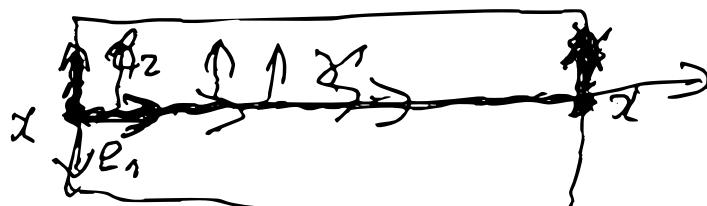
$g = g_E$

$g$  is deg on  $M$

$g$  is flat  $R = 0$

$$\Rightarrow \text{Hol}_x(g) = \{\text{id}\} \quad \text{Hol}_x(g) = 0$$

$$\begin{aligned} \pi_1(M, x) &\rightarrow \text{Hol}_x(g)/\text{Hol}_x^0(g) = \\ &= \text{Hol}_x(g) \end{aligned}$$



$$\pi_1(M, x) = \mathbb{Z}$$

$$T_\delta l_1 = l_1$$

$$T_\delta l_2 = -l_2$$

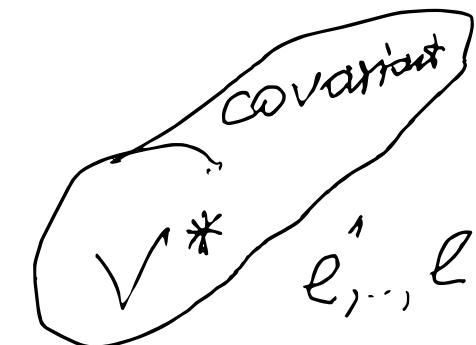
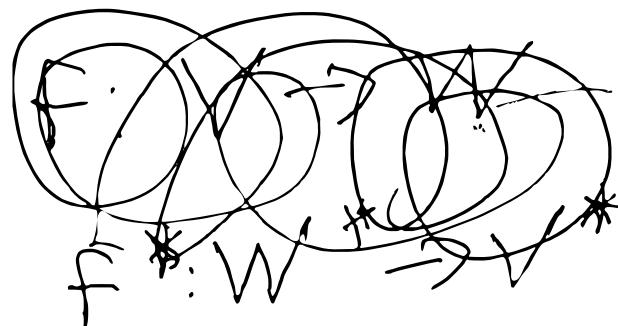
$$T_\delta = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\begin{aligned} T_\delta^2 &= \text{id} \quad \Rightarrow \text{Hol}_x(g) = \{\text{id}, T_\delta\} = \mathbb{Z}_2 \\ T_\delta &\notin \text{SO}(2) \end{aligned}$$

$$(p, 0) \quad (0, q)$$

Vektor  
is covariant

$\checkmark$  vector space  
 $x \in V \quad (1, 0)$



$$V \quad e_1, \dots, e_n \quad f_1, \dots, f_n$$

$$x = x^i e_i$$

$$\partial = \partial_j e^j$$

$$\partial(x) = x^j \partial_j$$

$$e'_1, \dots, e'_n$$

$$e^{i'}, \dots, e^{n'}$$

$$e_i = A_{i'}^i e^{i'}$$

$$A_i^{j'} A_{i'}^k = \delta_i^k$$

$$e_i = A_{i'}^i e^{i'}$$

$$x^i = A_{i'}^i x^{i'}$$

$$D_i = A_{i'}^j D_{i'}$$